# 05 Timer and counter output instructions

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## **Timer output instruction**

## **OUT T/Timer output**

When the calculation result before the OUT instruction is ON, the coil of the timer/retentive timer specified in (d) will be ON and measurement will be performed until the set value is reached. If the time limit expires, the normally open contact will conduct and the normally closed contact will become non-conductive.

-[OUT (d) (value)]

## Content, range and data type

Parameter		Content						Range			
(d)		Timer device num	Timer device number								
(value)		Timer setting value	Timer setting value								
Device u	sed										
Instruction	Parameter	Devices									
		KnX	KnY	KnM	KnS	т	С	D			
OUT T	Parameter 1					•					
	Parameter 2	•	•	•	•		•	•			

## Features

When the operation result before the OUT instruction is ON, the coil of the timer specified in (d) will be ON and measurement will be performed until the set value is reached. If the count reaches (current value  $\geq$  set value), the normally open contact will be conductive, and the normally closed contact will become non-conductive.

When the operation result before the OUT instruction changes from ON to OFF, the situation is as follows.

Timer type	Timer coil	The current value of the timer	<b>Bttio</b> re the time limit
			Normally o <b>psæ</b> d contact
Timer	OFF	0	<b>Non</b> ducti conductiv
Cumulative timer	OFF	Keep current value	<b>Son</b> ducti conductiv

• After the time limit expires, clear the current value of the accumulative timer and turn off the contact with the RST instruction.

• When the setting value is 0, the time limit will expire when the OUT instruction is executed.

• While the OUT T instruction is ON, if the OUT T instruction is skipped by the CJ instruction, etc., the current value update and contact ON/OFF will not be performed.

• If the same OUT T instruction is executed more than twice in the same scan, the current value will be updated according to the number of executions.

• Description of each timer:

Device number	Timer specifications
T0 to T191	100ms timer
T192 to T199	100ms subroutine timer (used in the subroutine, even if the subroutine is not called, it will still be upd

Content

The parameter setting in (value) is out of range

T200 to T245

10ms timer

## Error code

Error code

4084H

## Example

Using timing, D0 increases by 1 after every 1S:

# **Counter output instructions**

## **OUT C/Counter output**

16-bit counter instruction: When the operation result before the OUT instruction changes from OFF to ON, the current value of the counter specified in (d) will be +1. If the count reaches, the normally open contact will be turned on and the normally closed contact will become Non-conductive.

## -[OUT (d) (value)]

## Content, range and data type

Paran (d) (value			<b>tent</b> nter devi nter setti			<b>Range</b> - 0 to 32767			<b>Data type</b> Counter Unsigned BIN 16 bit			<b>Data type (label)</b> ANY ANY_INT			
Dev	vice used														
InstructPranametitervices Offset Pulse									t Pulse						
													mo	dificentiteensio	on
	KnX	KnY	KnM	KnS	Т	С	D	R	SD	к	н	Е	[D]	ХХР	
OUT C	Parameter 1					•									
	Parame∎r 2	•	•	•	•		•	•	•	•	•	•			

Features

• When the calculation result before the OUT instruction changes from OFF to ON, the current value (count value) of the counter specified in (d) will be +1. If the count reaches (current value ≥ set value), the normally open contact will be turned on , The normally closed contact becomes non-conductive.

• If the calculation result is ON, no counting is performed. (Counting input does not need to be pulsed.)

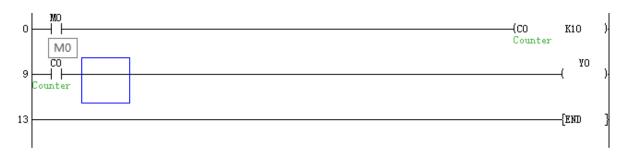
• After the count is reached, the count value and the state of the contact do not change before the RST instruction is executed.

• When the setting value is 0, the processing is the same as when it is 1.

# Error codeContent4084HThe parameter setting in (value) is out of range4085HThe (value) parameter exceeds the device range

#### Example

Error code



Every time M0 changes from OFF $\rightarrow$ ON, C0 will increase by 1. When the value of C0 is added to K10, the normally open contact of C0 is closed and Y0 is output. At this time, M0 continues from OFF $\rightarrow$ ON, and the value of C0 will not change anymore.

The contact of C0 can only be turned OFF by RST/ZRST instruction and communication.

## **OUT LC instruction/Long counter output**

32-bit counter instruction: When the operation result before the OUT instruction changes from OFF to ON, the current value of the long counter specified in (d) will be +1. If counted, the normally open contact will be turned on and the normally closed contact will change It is non-conductive.

-[OUT (d) (value)]

#### Content, range and data type

Parameter Content				Range			Data type			Data type (label)				
(d)		Long num	g counte ber	r device		-	Counter			ANY				
(value)	)	Long value	g counte e	r setting		0 to 42949	967295		Unsigne	d BIN 3	2 bit	ANY_	INT	
Dev	rice used													
Instru	c <b>fRan</b> ame <b>De</b> rvice	s											Offse	et Pulse
													mo	odificeatxiteem sion
	KnX	KnY	KnM	KnS	т	D	R	SD	LC	К	н	Е	[D]	ХХР
OUT LC	Parameter 1								•					
	Parame <b>t●</b> r 2	•	•	•	•	•	•	•		•	•	•		

#### Features

• When the calculation result before the OUT instruction changes from OFF to ON, the current value (count value) of the long counter specified in (d) will be +1. If the count reaches (current value ≥ set value), the normally open contact will turn on On, the normally closed contact becomes non-conductive.

• If the calculation result is ON, no counting is performed. (Counting input does not need to be pulsed.)

• After the count is reached, the count value and contact status will not change before the RST instruction or ZRST instruction is executed.

• When the setting value is 0, the processing is the same as when it is 1.

Error	code
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Error code	Content
4085H	The (value) parameter exceeds the device range

## Example

Each time M0 changes from OFF to ON, LC0 will increase by 1. When the value of LC0 is added to K10, the normally open contact of LC0 is closed and Y0 is output. At this time, M0 continues from OFF $\rightarrow$ ON, and the value of LC0 will not change anymore.

The contact of LC0 can only be turned OFF by RST/ZRST instruction and communication.